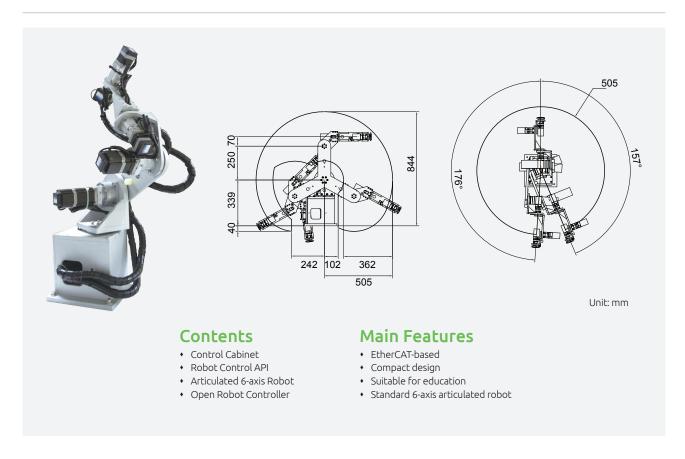
MiniBOT Robot



Product Overview

EtherCAT Communication

Based on standard EtherCAT communication, MiniBOT provides an expandable distributed control system. It is also a good material for EtherCAT-related training.

Industrial Robot Design

By referring to design of general industrial 6-axis articulated robots, MiniBOT is built in the same concept. Its nude mechanical architecture makes it easy to learn the structure of an industrial robot.

Open Development Environment

MiniBOT comes with a utility tool to directly operate the robot. Robotic control APIs are also provided in Windows platform, so that users can leverage its openness to develop any kind of robot applications.

Specifications

Robot Arm

- Degree of Freedom: 6
- Payload: 1kg
- Driving System: EtherCAT close-loop stepper
- Position Feedback: Incremental encoder
- Operation Range: 590mm(Maximum)

J1: ±175°

J2: +110°~ -92°

J3: +63°~ -153°

J4: ±175°

J5: ±92°

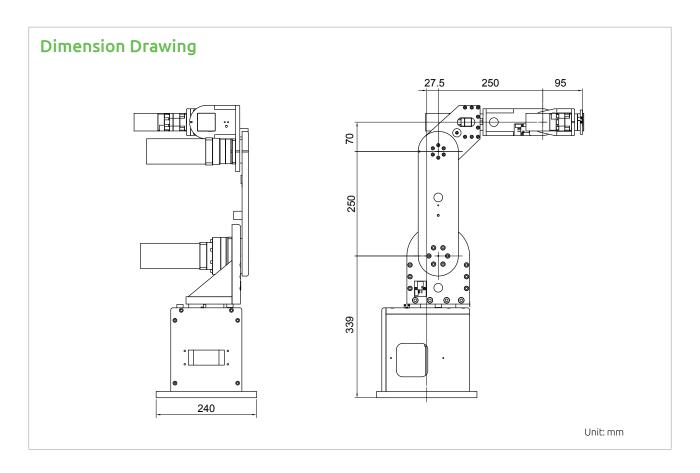
- Repeatability: ±0.12mm
- Weight: Arm 30kg
- Input Voltage: Single phase 100 ~ 240Vac

Controller

- DI/O: 15-ch DI/16-ch DO(DB37 Connector)
- 1 x Intel® GbE LAN port
- 1 x VGA
- 2 x USB2.0 (External)
- 1 x USB3.0, 1 xUSB2.0 (Inside Cabinet)
- 1 x Emergency Stop Bottom
- Weight: Control cabinet 20kg

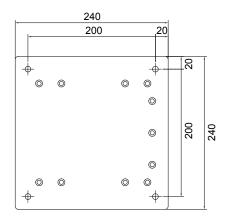
Software

- NexGRC runtime(Robot control runtime)
- NexMotion Studio(Configuration Utility)
- Provide standard robot motion control functions
- Support C\C++,C# and VB.Net for user programming
- OS: WES7



Installation

• Installation: Floor-mounting



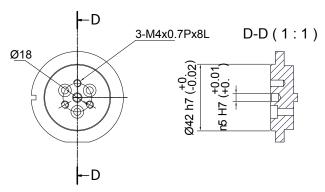
Ordering Information

Robot Package

MiniBOT Robot Package(P/N: 7900000179X00)

Optional

- Base Table 70x70x78 cm (P/N:TBC)
- DB-37 cable 1m/3m (P/N: TBC)
- DB-37 terminal board (P/N: TBC)



Unit: mm